

### AMENDMENTS TO THE SPECIFICATION

The specification has been amended as follows:

#### Page 1

The paragraph at lines 7-19 has been amended as follows:

Fig. 2 schematically illustrates an example of conventional cam rotation control mechanism. A cam 21 comprises two plate cams joined together, ~~i.e. a~~ i.e., a cam 21a having an eccentric shape and a circular cam 21b formed with a notch 21c. The cam 21 has a center of rotation indicated by a point of intersection of two phantom lines in the figure, to which a non-illustrated rotating shaft is attached. An arm 22 has a tip end portion constantly abutting the outer circumference of the cam 21a by its own weight. As the rotational position (angle) of the cam 21a varies, the arm 22 moves in the vertical direction (up and down) in the figure. The cam 21 is driven for rotation in the counterclockwise direction by a non-illustrated driver such as a motor.

#### Page 3

The paragraph at lines 2-15 has been amended as follows:

Fig. 3 is a schematic view illustrating an example of conventional cam rotation control mechanism which differs from that shown in Fig. 2. A cam 31 comprises two plate cams joined together, ~~i.e. a~~ i.e., a cam 31a having an eccentric shape and a cam 31b in the form of a circle partially cut away. The cam 31 has a center of rotation indicated by a point of intersection of two phantom lines in the figure, to which a non-illustrated

rotating shaft is attached. An arm 32 has a tip end portion constantly abutting the outer circumference of the cam 31a by its own weight so that the arm 32 is movable in the vertical direction (up and down) in the figure. When receiving driving power from a non-illustrated driver such as a motor, the cam 31 rotates in the counterclockwise direction, for example.

Page 7

The heading at line 12 has been amended as follows:

DETAILED DESCRIPTION OF THE ~~PREFERRED EMBODIMENTS~~INVENTION